

SUMO CONFERENCE 2024

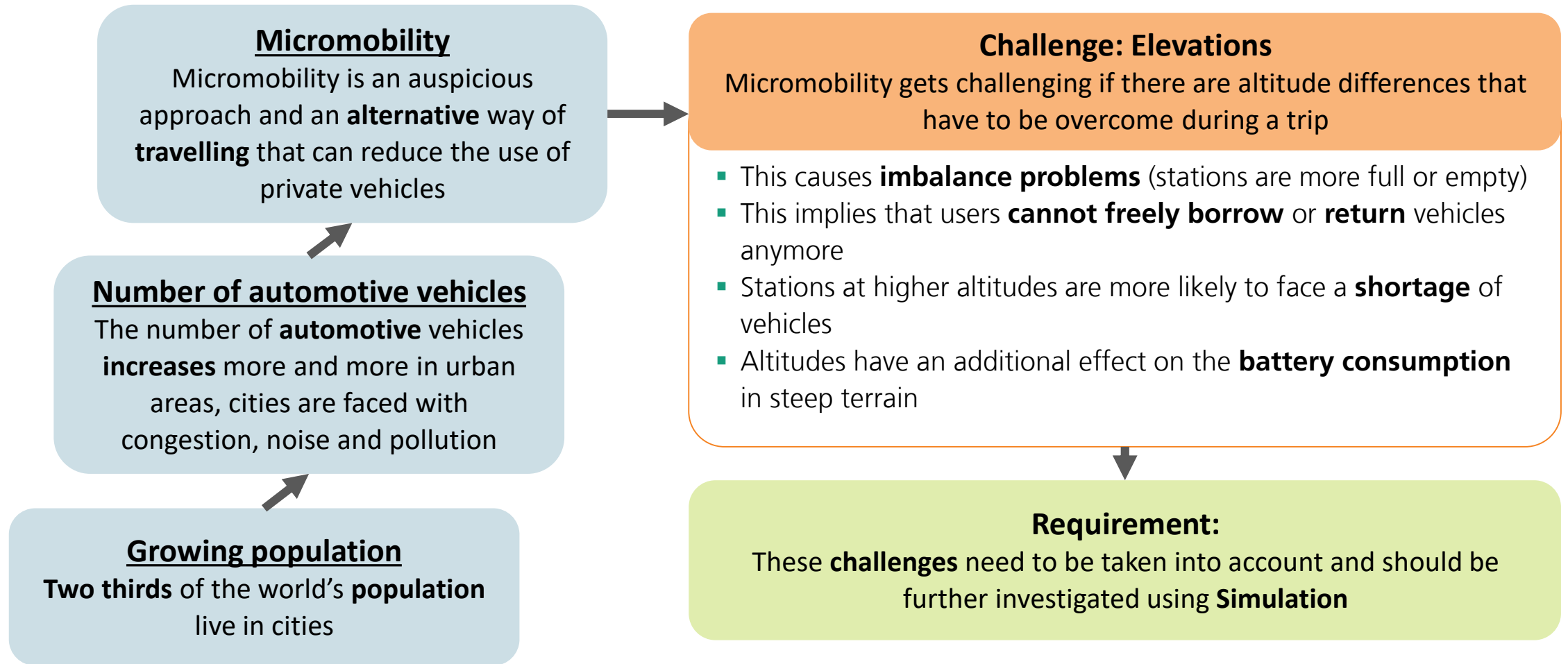
Integrating Topographical Map Information in SUMO to
Simulate Realistic Micromobility Trips in Hilly and
Steep Terrains

—
Andreas Freymann
Damir Ravlija



Introduction

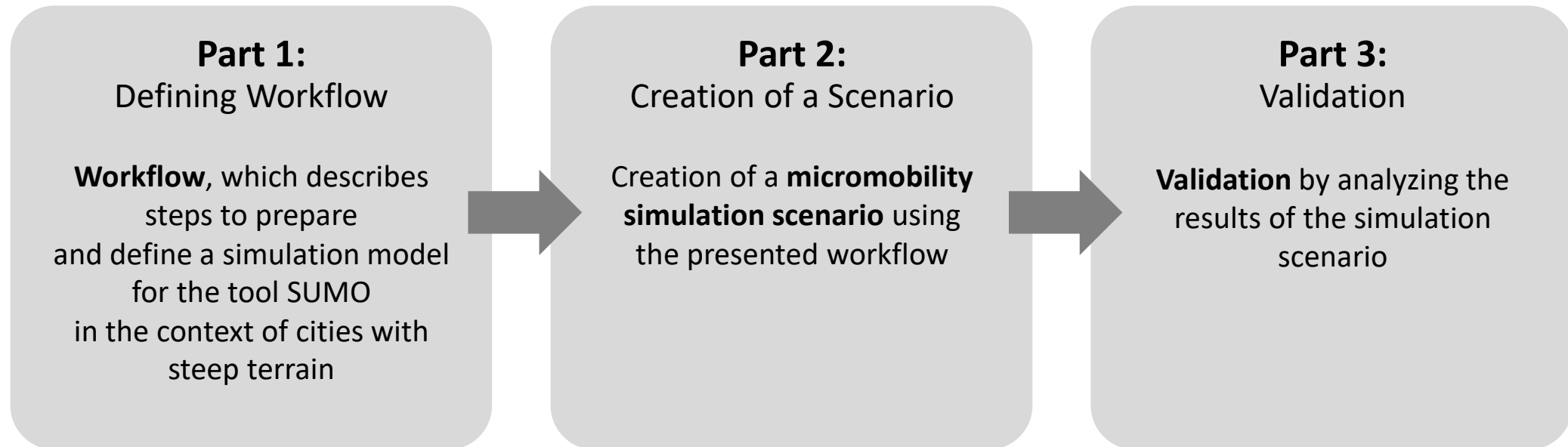
Motivation and Problem Definition



Introduction

Parts of the work

- This paper investigates micromobility for electric vehicles in combination with hilly and steep terrain.
- There are three important parts this work is dealing with:



Micromobility Scenario with Topographical Map Information

Using Stuttgart as Example

- For the simulation of micromobility a map with different altitudes is necessary
- We choose an area of Stuttgart as Stuttgart has the following characteristics
 - Interesting topographic structures with **altitude differences** of more than **300 meters**
 - The **center** of Stuttgart lies in a sink at a height of **245 meters**
 - There are **different valleys** with various lengths and different elevations

Figure 1 shows the different altitudes in and around Stuttgart. Especially, the southeast of Stuttgart has various and changing altitudes.

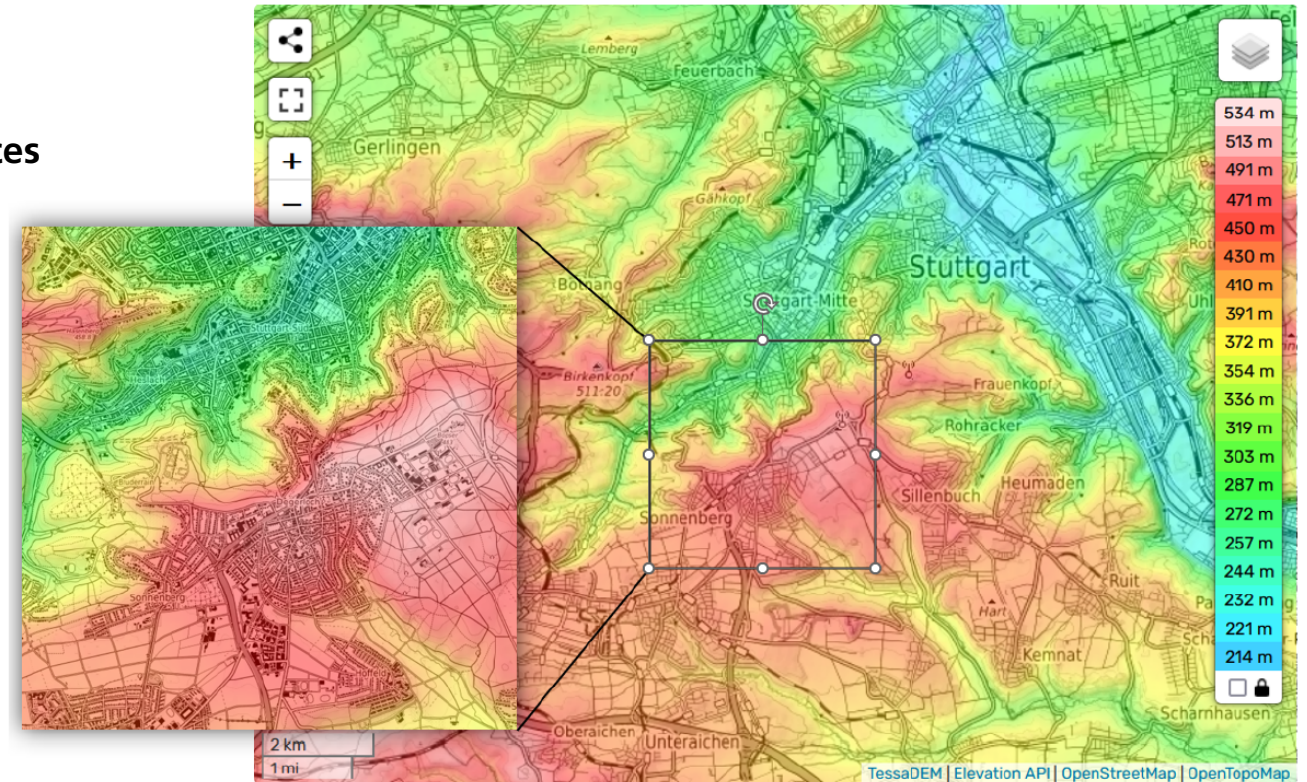


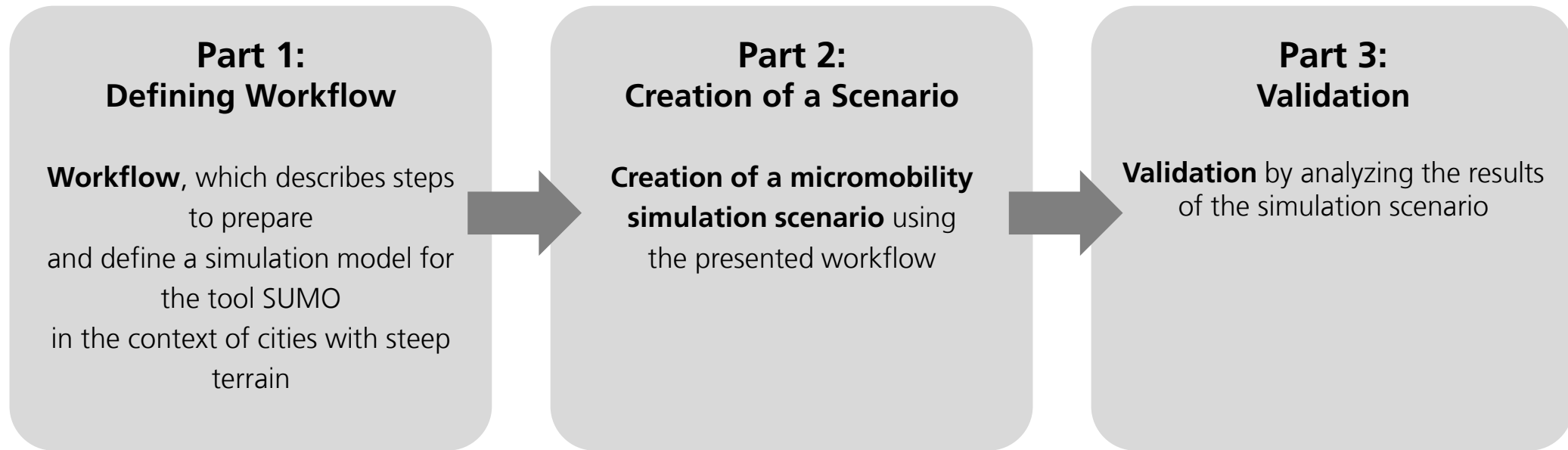
Figure 1. Topography of Stuttgart and its different altitudes

Stuttgart



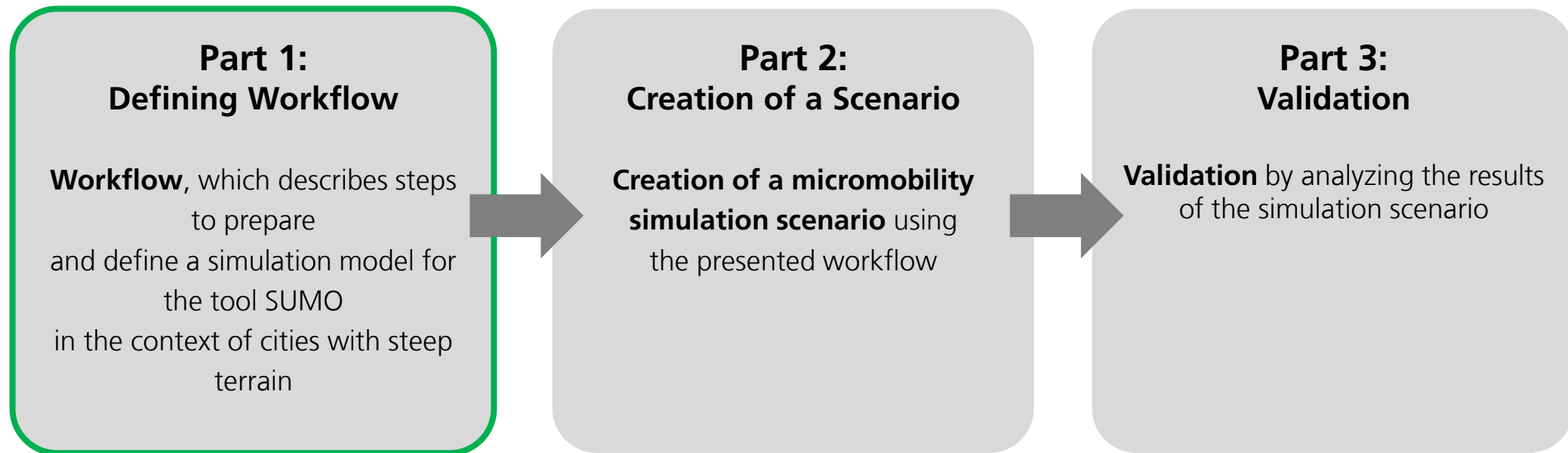
Part 1

Defining Workflow



Part 1

Defining Workflow



Part 1

Defining Workflow

Part 1:
Defining
Workflow

The workflow consists of **three steps**:

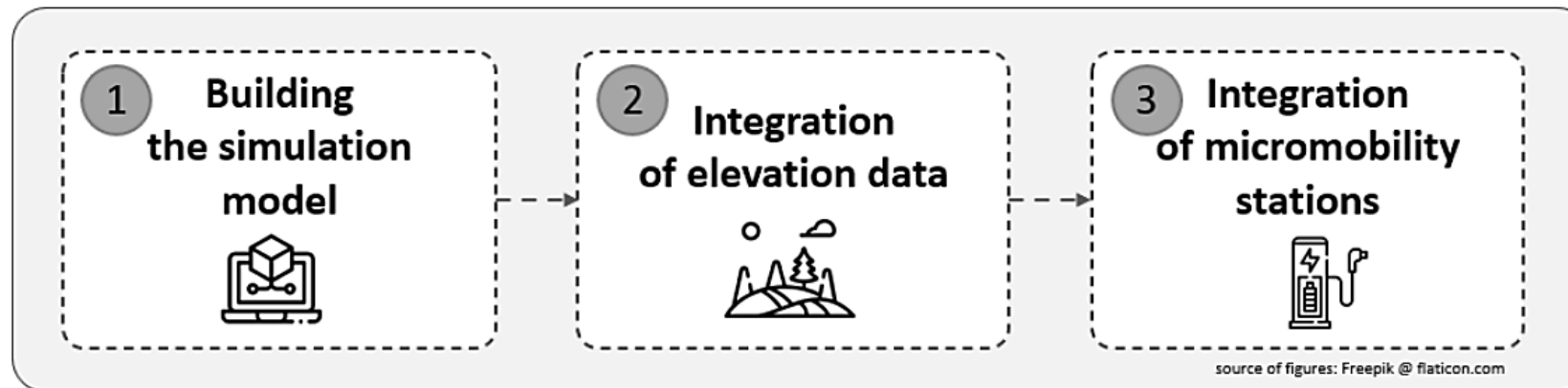
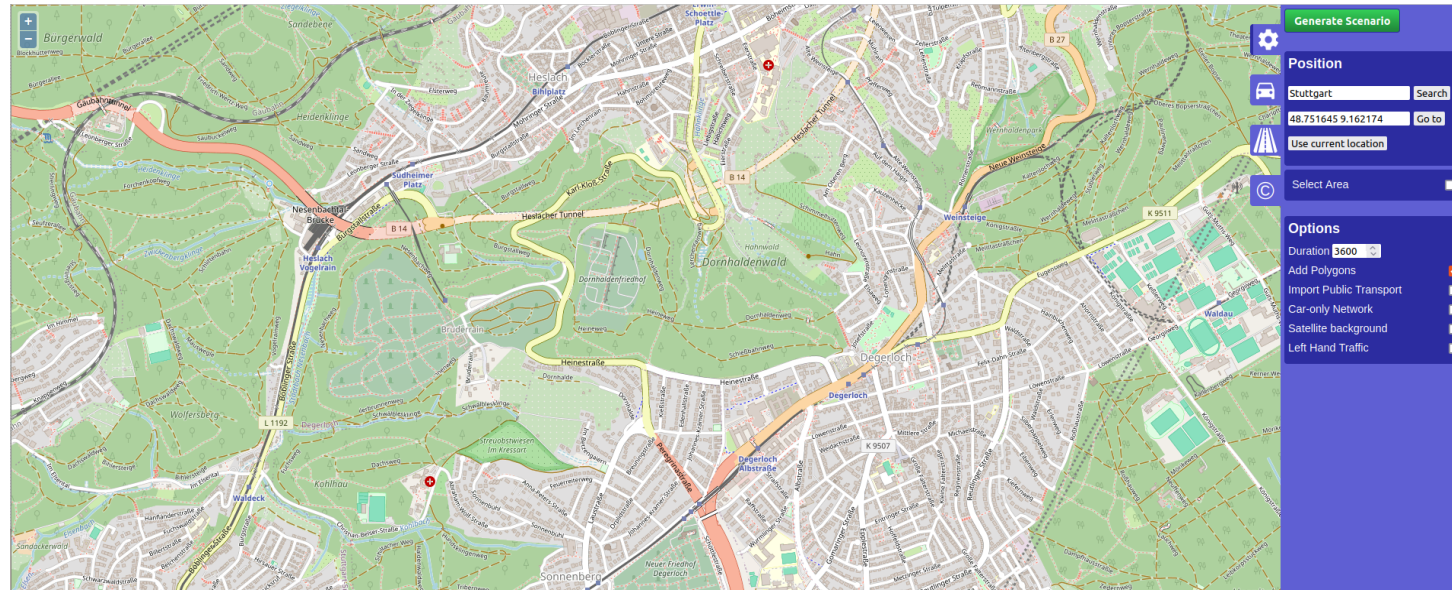


Figure 2. Steps and validation of the workflow

Part 1 – Defining Workflow

Building the simulation model

Part 1:
Defining
Workflow



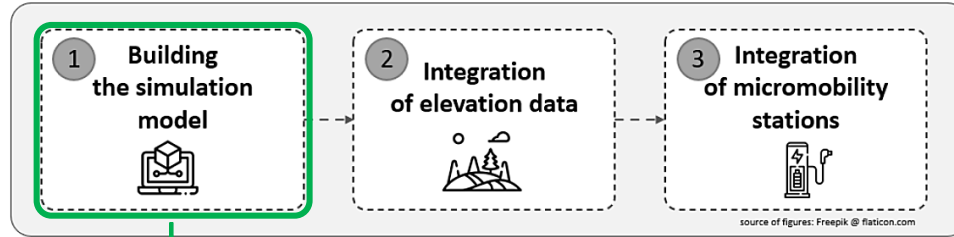
OSMWebWizard



Initial Net File

Part 1 – Defining Workflow

Building the simulation model



```
<?xml version="1.0" encoding="UTF-8"?>
```

```
<routes xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance" xsi:  
noNamespaceSchemaLocation="http://sumo.dlr.de/xsd/routes_file.xsd">
```

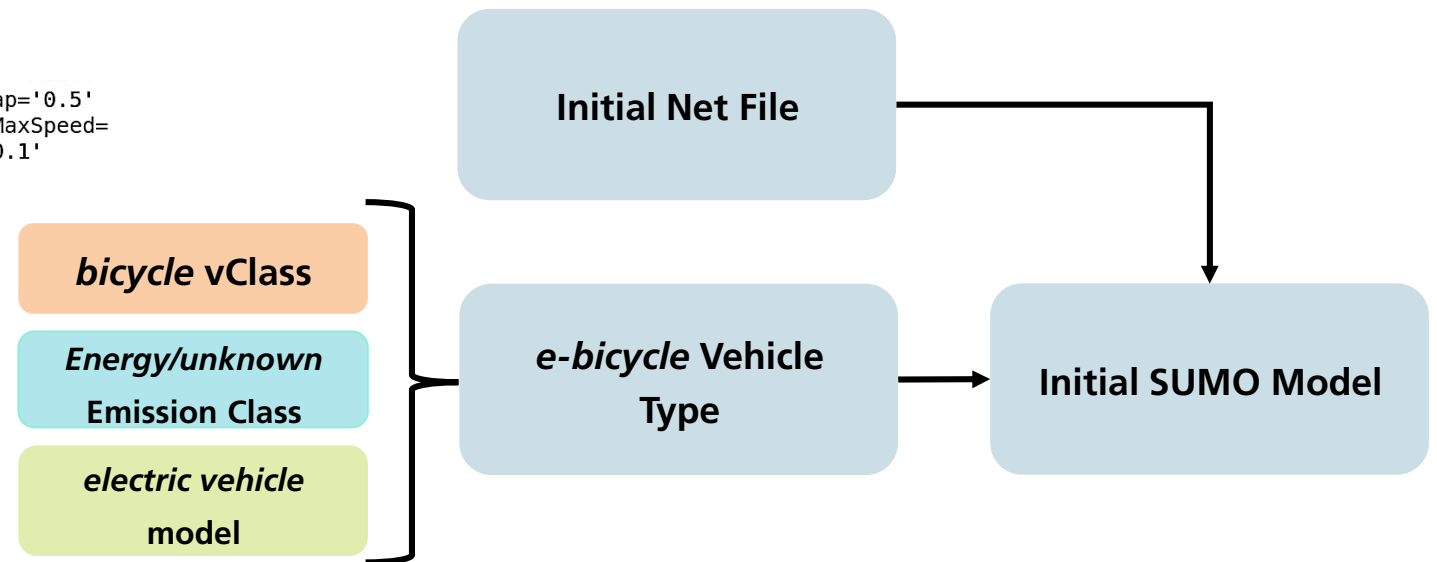
```
<vType id="e_bicycle" length='1.6' width='0.65' height='1.7' minGap='0.5'  
accel='1.2' decel='3' emergencyDecel='7' maxSpeed='13.89' desiredMaxSpeed=  
'5.56' emissionClass='Energy/unknown' vClass='bicycle' speedDev='0.1'  
color='1.1.1'>
```

```
<param key="has.battery.device" value="true"/>  
<param key="device.battery.capacity" value="400"/>  
<param key="maximumPower" value="250"/>  
<param key="vehicleMass" value="100"/>  
<param key="frontSurfaceArea" value="0.5"/>  
<param key="airDragCoefficient" value="1.1"/>  
<param key="internalMomentOfInertia" value="0.01"/>  
<param key="radialDragCoefficient" value="0.1"/>  
<param key="rollDragCoefficient" value="0.01"/>  
<param key="constantPowerIntake" value="100"/>  
<param key="propulsionEfficiency" value="0.98"/>  
<param key="recuperationEfficiency" value="0"/>  
<param key="stoppingThreshold" value="0.1"/>
```

```
</vType>
```

```
<trip id="test_ebike" type="e_bicycle" depart="0.00" departLane="best"  
from="4821895#1" to="-96266013#0"/>
```

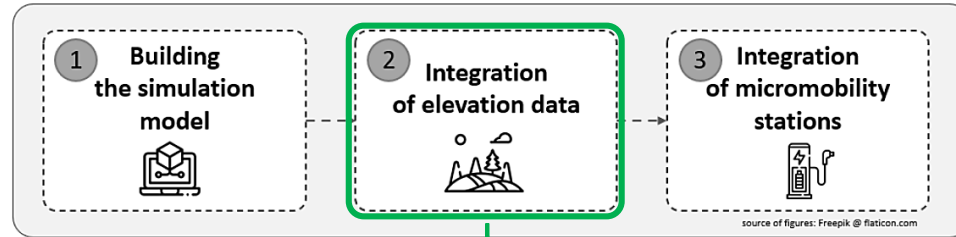
```
</routes>
```



Part 1 – Defining Workflow

Integration of the Elevation Data

Part 1:
Defining
Workflow



- SUMO **provides** a capability to process elevation data from the OSM data by using the **"ele"-tag**
- However, the **elevation** is used for **prominent topological areas** (mountain ranges and peaks)
- For a more **realistic** simulation model, we add the topography information to **all available geographical locations** within the SUMO model
- We used an Open Topo Data REST-service
- We divided it into three parts

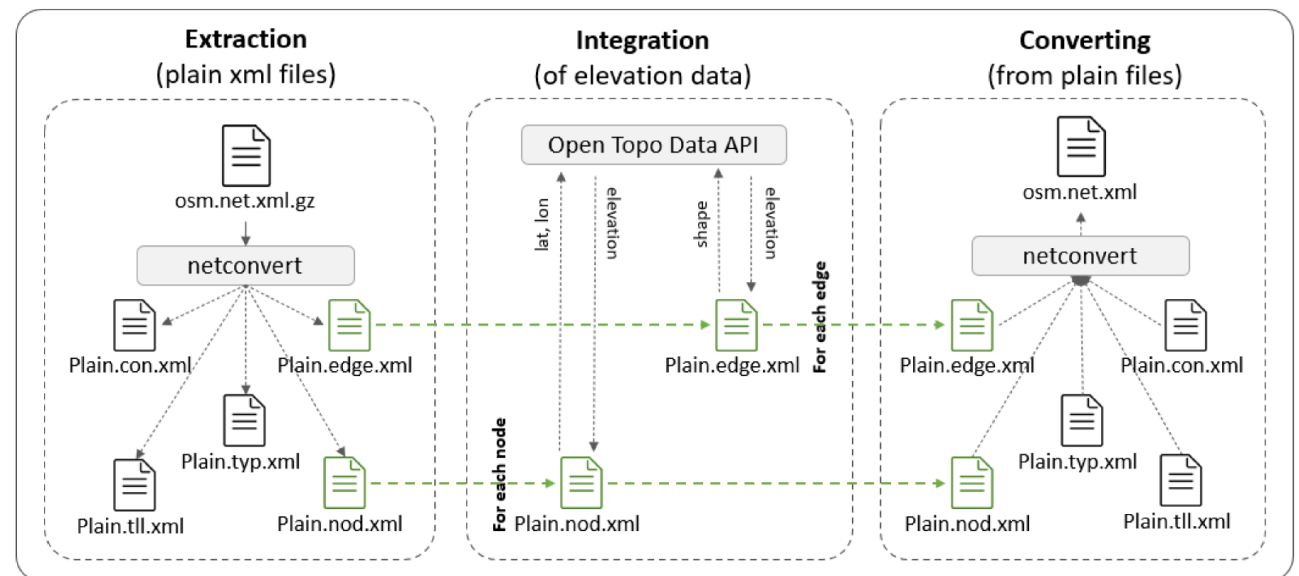
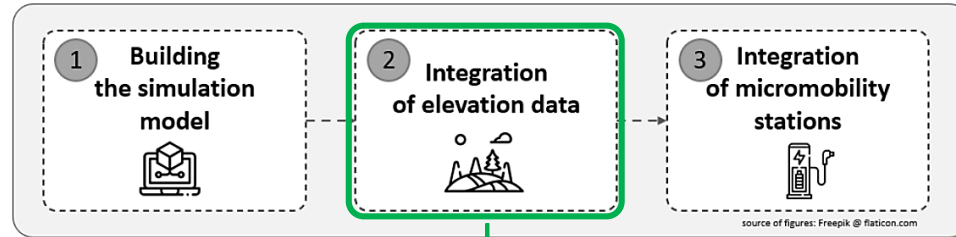


Figure 4. Overview over the steps to integrate elevation data

Part 1 – Defining Workflow

Integration of the Elevation Data

Part 1:
Defining
Workflow



Extraction

- Extracts **five plain files** from the osm.net.xml.gz file using the **netconvert** -s command with the --plain-output-prefix attribute.
- The plain files contain concrete information about the network topology and geometry

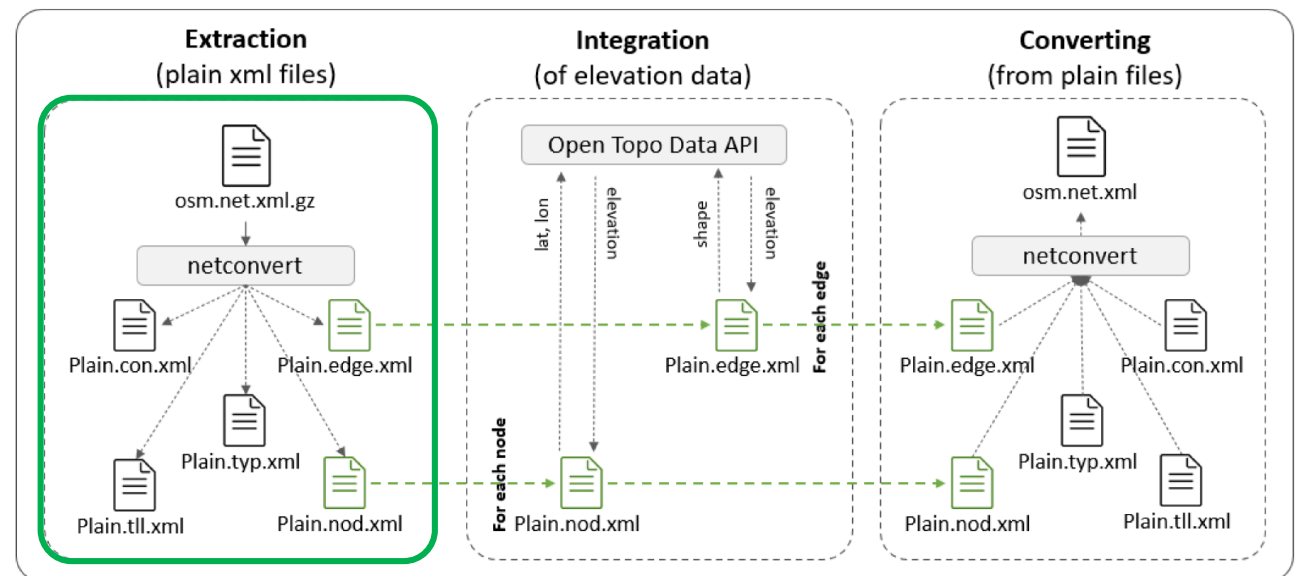
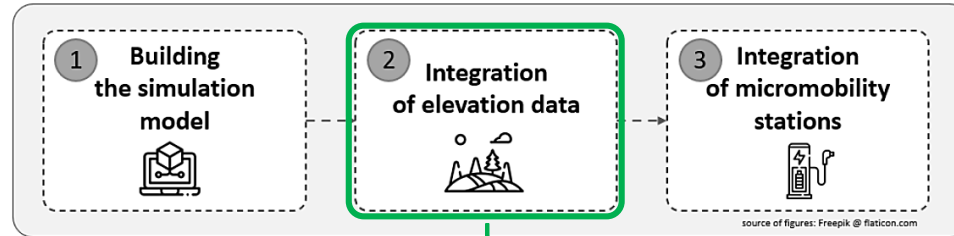


Figure 4. Overview over the steps to integrate elevation data

Part 1 – Defining Workflow

Integration of the Elevation Data

Part 1:
Defining
Workflow



Integration

- The **node.xml** and **edge.xml** are the files of interest as they contain geographical information
- For the **node.xml** and **edge.xml** the elevation are fetched from the API
- **node.xml file:**
 - All nodes have geographical points **(x, y)**
 - The elevation is added by a „z“: **(x, y, z)**
- **edge.xml file:**
 - An edge has geographical points within a shape: **(x1,y1 x2,y2 x3,y3)**
 - The elevation is added by a „z“: **(x1,y1, z1 x2,y2, z2)**

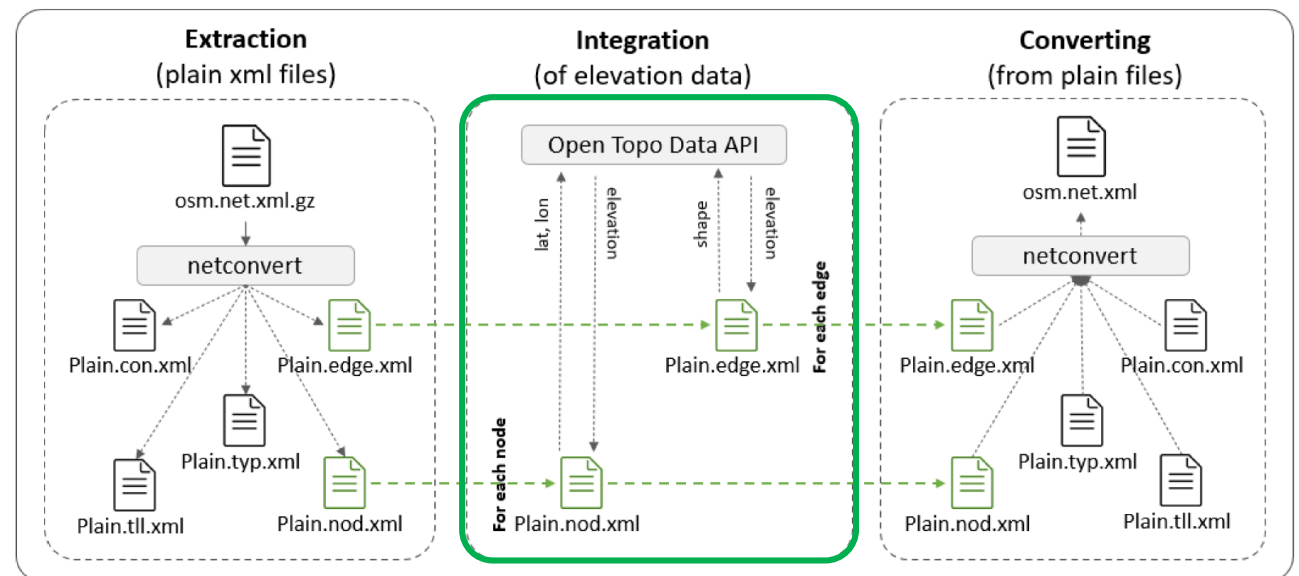
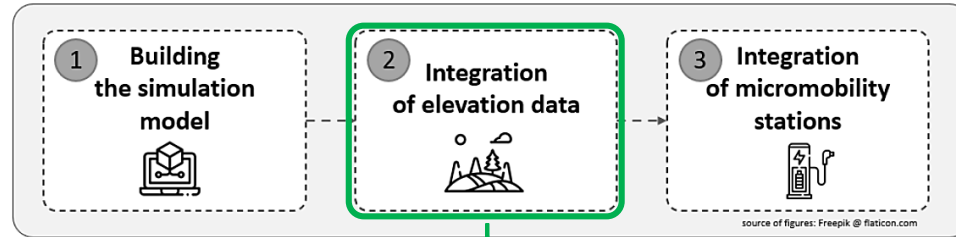


Figure 4. Overview over the steps to integrate elevation data

Part 1 – Defining Workflow

Integration of the Elevation Data

Part 1:
Defining
Workflow



Converting

- Uses the **netconvert** command to convert the five plain files back to the **osm.net.xml** file
- by using certain command attributes for the existing plain files such as **--node-files** for the node file.
- **Result:**

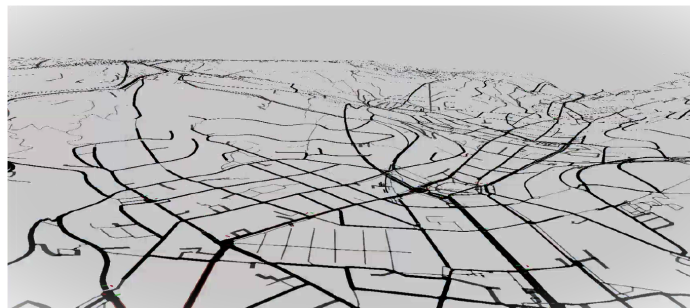


Figure 5. SUMO model enriched with elevation data displayed in sumo-gui with 3D view

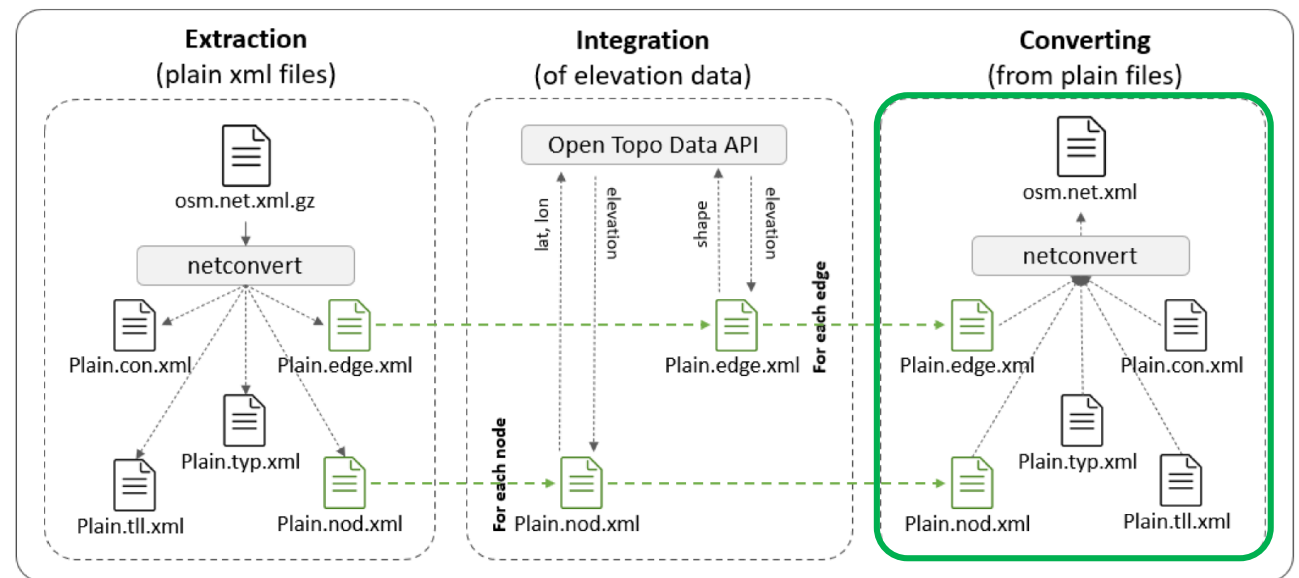
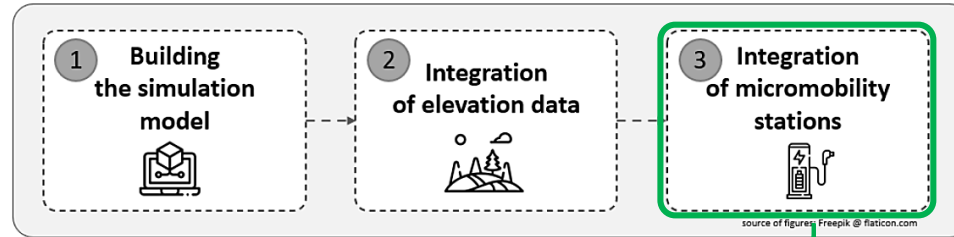


Figure 4. Overview over the steps to integrate elevation data

Part 1 – Defining Workflow

Integration of Micromobility Stations

Part 1: Defining Workflow



Integration

- Using OSM data or General Bikeshare Feed Specification Data (GBFS)
- GBFS Advantages:
 - Up-to-date station data
 - Possibly further data like number and type of available vehicles at the station
- RegioRadStuttgart
- Process:
 - Reads **station_information.json** and the SUMO net file
 - Maps station locations to SUMO edges
 - Outputs an xml file with stations as *points of interest*

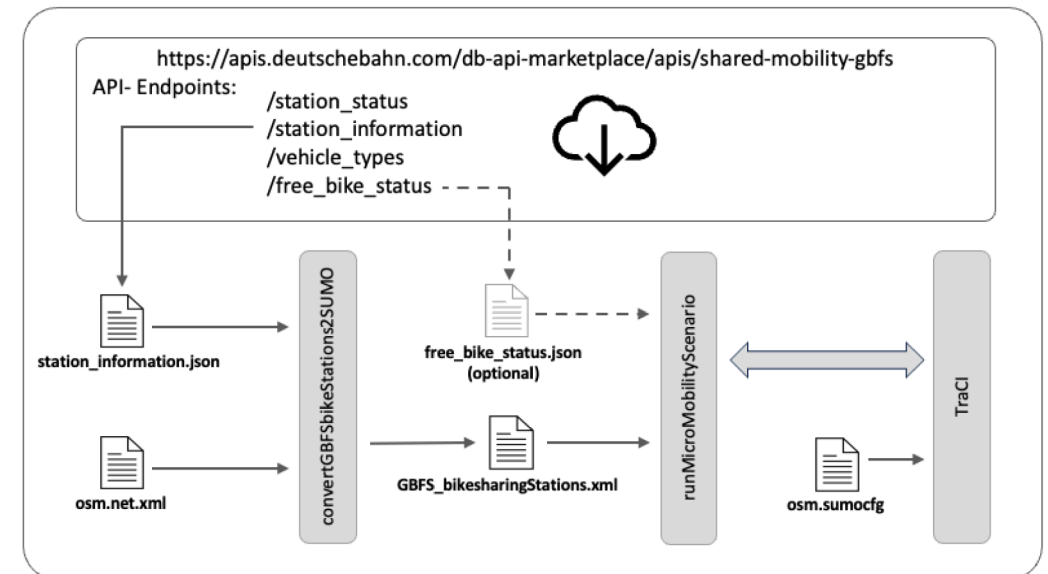
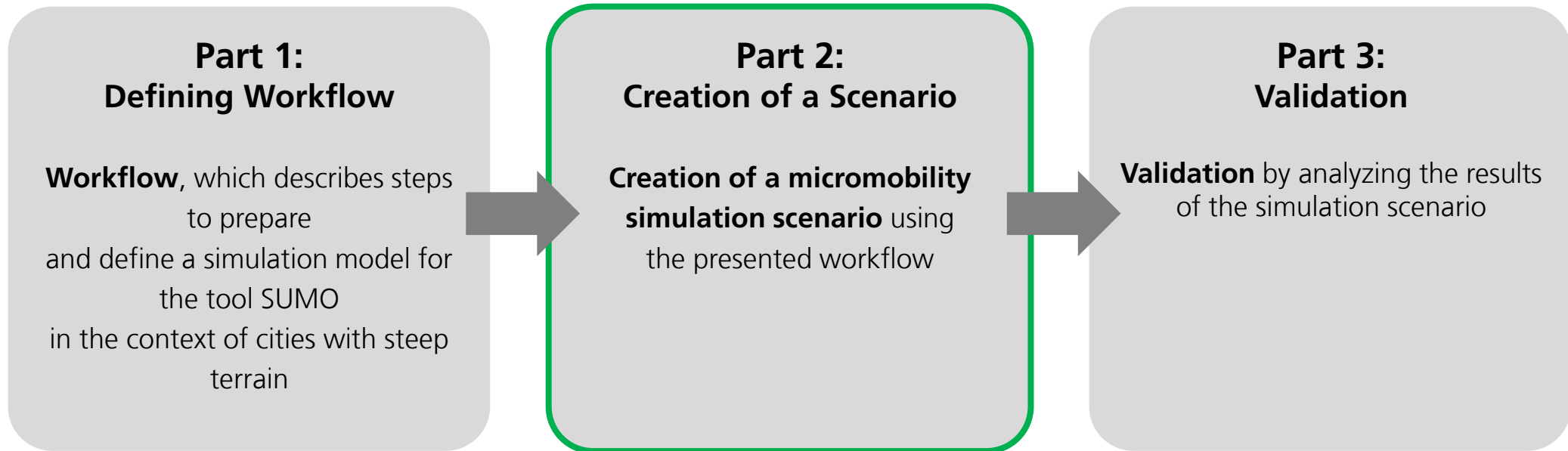


Figure 6. Workflow to utilize GBFS-Data for SUMO Micromobility Simulations

Part 2

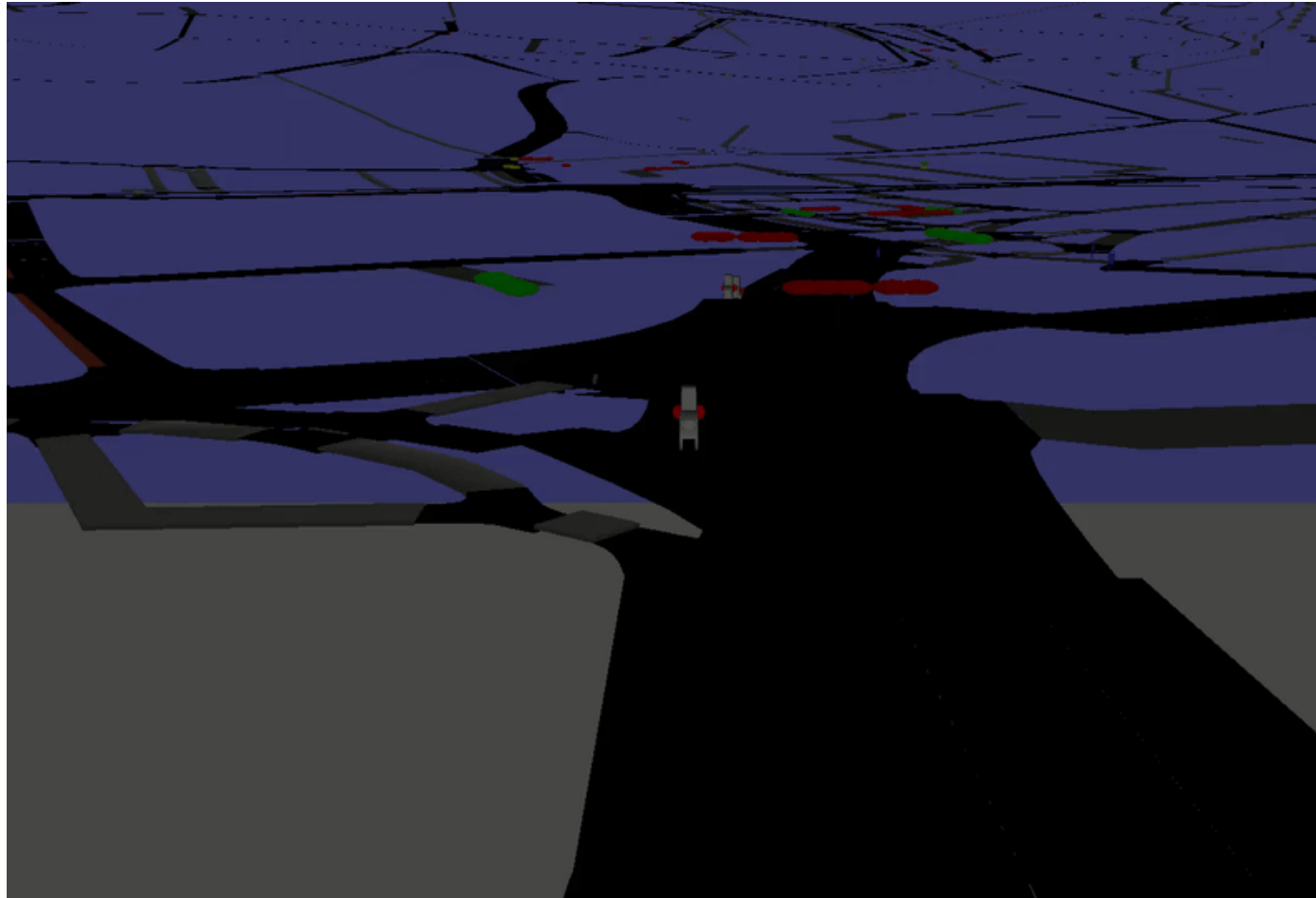
Creation of a Scenario



Part 2

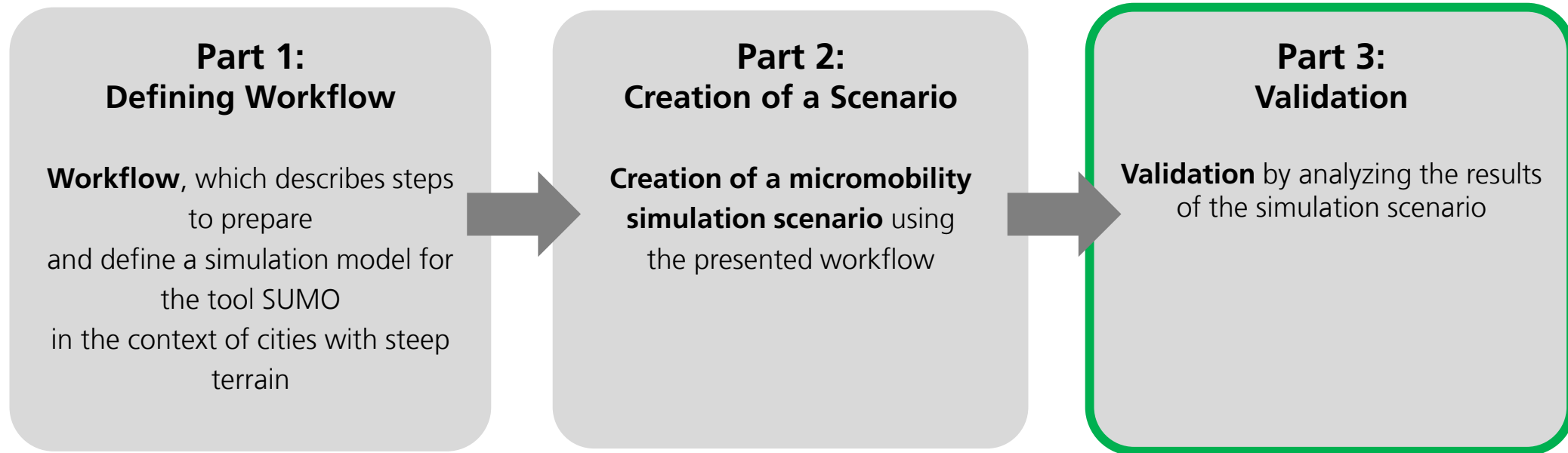
Creation of a Scenario

Part 2:
Creation of a
Scenario



Part 3

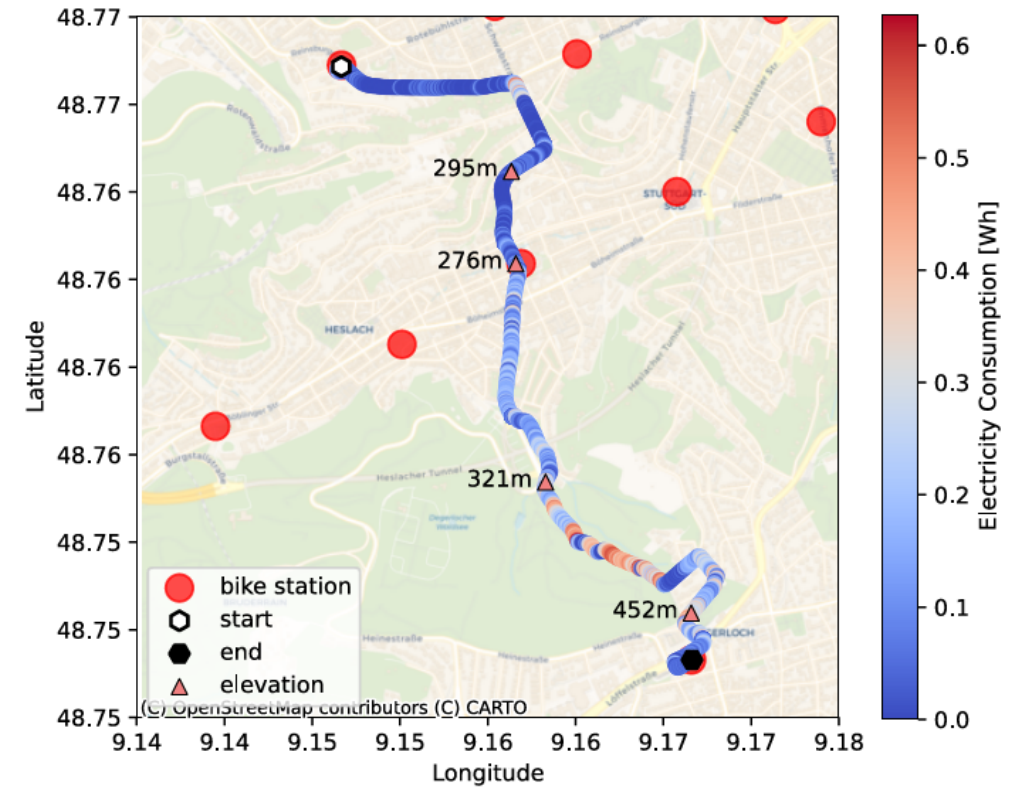
Validation



Validation

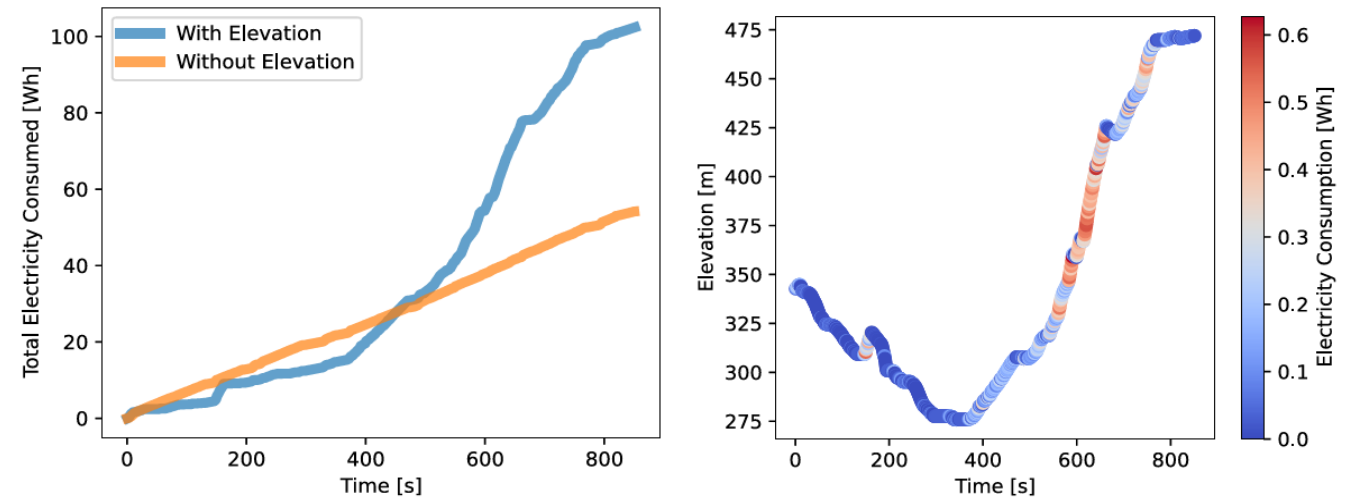
What and Where

- With micromobility trips between docking stations
- **Validation of the workflow**
 - By checking:
 - Altitude differences
 - Availability of docking stations
 - Energy consumption of the e-bicycle
- Route between two elevated docking stations
 - Route lowest point at 276m
 - Route highest point at 472m



Validation Comparison

- Comparison
 - With elevation data
 - Without elevation data
- Electricity consumption without elevation data grows linearly with time – **unrealistic**
- No recuperation -> no negative electricity consumption
 - Still, **reduced** consumption
- Electricity consumption **dependent** on the **slope**



(a) Electricity consumption over time

(b) Elevation change over time

Figure 8. Consumption and elevation change over time

Conclusion

- **Workflow for the inclusion into SUMO simulation models**
 - Elevation data
 - Docking station data
- **Elevation data from REST API**
 - No need for expensive topographical map data
- **Validation with a scenario using an e-bicycle vehicle type in a hilly area**
 - Comparison with and without elevation

Future Work

Possible working contents for the future

More infrastructure

Considering of more infrastructure details such bridges or tunnels

Elevation feature

Integration of an elevation feature within the OSMWebWizard (without request limitation)

Tool for micromobility fleet scenarios

Tool to generate shared micromobility fleet scenarios from origin-destination tables representing customer interests

Driving behaviour

Considering of the driving behaviour (speed and acceleration) of micromobility behaviour



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Related Work (Damir)

Topic elevations and bicycles

In reference to elevations

- **Monaco SUMO Traffic (MoST) Scenario** [1]
 - First freely-available mobility scenario for SUMO with elevation
 - The scenario covers an area of approximately 70 km²
 - It contains predefined routes for pedestrians, for different kinds of vehicles and for the local public transport system
- **SUMO Activity Generation (SAGA) framework** [2]
 - Is based on the MoST scenario
 - Provides a workflow and a tool chain to create complex multi-modal activity-based simulation scenarios
 - SAGA extracts streets infrastructure and environmental features (e.g., parking areas, buildings, and Pols)
 - It supports multiple travel modes (i.e., walking, cycling, public transport, on-demand mobility and user-defined vehicles)

In reference to bicycle modeling

- **The State of Bicycle Modeling in SUMO** [3]
 - Stated that micromobility vehicle types are becoming more and more important within simulations
- **Framework for Simulating Cyclists in SUMO** [4]
 - Allows a more realistic modelling of cyclists by allowing a higher degree of freedom of movement
 - They considers cyclists and their behavior intermediate between motorized vehicles and pedestrians.

[1] L. Codeca and J. Haerri, "Monaco SUMO Traffic (MoST) Scenario: A 3D Mobility Scenario for Cooperative ITS," *en*, 2018, pp. 43–29. DOI: 10.29007/1zt5.

[2] L. Codeca, J. Erdmann, V. CAHILL, and J. Haerri, "Saga: An activity-based multi-modal mobility scenariogenerator for sumo," *SUMO Conference Proceedings*, vol. 1, pp. 39–58, 2022. DOI: 10.52825/scp.v1i.99.

[3] A. Roosta, H. Kath, M. Barthauer, J. Erdmann, Y.-P. Flötter, and M. Behrisch, "State of bicycle modeling in sumo," *SUMO Conference Proceedings*, vol. 4, pp. 55–64, 2023. DOI: 10.52825/scp.v4i.215

[4] H. Kath and A. Roosta, "Framework for simulating cyclists in sumo," *SUMO Conference Proceedings*, vol. 4, pp. 105–113, 2023. DOI: 10.52825/scp.v4i.219.

Commands

Converting Plain Files

Extract plain files from OSM File

```
"netconvert -s PATH_TO_OSM_FILE+ " --plain-output-prefix " + PATH_TO_PLAINFILES_DIR + "/PLAIN"
```

Convert plain files to OSM File

```
netconvert
```

```
--node-files=PATH_TO_PLAIN-NODE-FILE
```

```
--edge-files=PATH_TO_PLAIN-EDGE-FILE
```

```
--connection-files= PATH_TO_PLAIN-CON-FILE
```

```
--type-files= PATH_TO_PLAIN-TYPE-FILE
```

```
--tllogic-files= PATH_TO_PLAIN-TLLOGIC-FILE
```

```
--output-file=PATH_TO_OSM_FILE + osm.net.xml
```