Integration Traffic Signal Control From Synchro to SUMO

Yiran Zhang May 15, 2024



Intelligent Urban Transportation Systems UNIVERSITY of WASHINGTON





SUMO User Conference **2024** 13-15 May • Berlin

Outlines

- > Introduction & Motivation
- > Traffic signal control integration
- > Conclusion & Future Step







Introduction & Motivation

> Current traffic simulation

- Macroscopic: Focuses on the traffic at a low level of detail where the traffic stream is represented in an aggregated level, such as speed, flow, and density.
- Microscopic: Details individual vehicle and pedestrian movements, allowing for the simulation of specific behaviors like car-following and lane-changing.
- Mesoscopic: A hybrid approach blending macroscopic and microscopic elements, offering more detailed analysis than macroscopic models but less resource-intensive than microscopic simulations.
- Submicroscopic: Provides intricate details of each vehicle, including internal mechanics such as gear shifting, suitable for in-depth vehicle dynamics analyses



Cont.

> When & Why is simulation integration needed?

- Large-Scale Simulations
 - Extracting network features from existing simulations vs. manual coding
- Multiscale Simulation Connectivity
 - Seamless connectivity and communication across different simulation platforms are crucial for multiscale simulations.
- Data sharing
 - When data providers offer information from different simulation platforms, it is essential for researchers to adeptly transfer these features to maintain data integrity and relevance.





Therefore

> The aim of this study

- Understand the feasibility and effectiveness of simulation integration, specifically traffic signal timing
- Identify potential obstacles and problems

> Case study

- Synchro vs. SUMO
- Traffic signal timing
- Study area
 - o Downtown Seattle, USA





Synchro vs. SUMO

> Synchro (widely used in public agency) → why we use synchro as feature transform

 "Synchro is a macroscopic analysis and optimization software application. Synchro supports the Highway Capacity Manual's (HCM) 6th Edition, 2010 and 2000 for signalized intersections, unsignalized intersections and roundabouts. Synchro also implements the Intersection Capacity Utilization method for determining intersection capacity." specifically in traffic signal optimization

> SUMO

 "Simulation of Urban MObility" (SUMO) is an open source, highly portable, microscopic and continuous traffic simulation package designed to handle large networks. It allows for intermodal simulation including pedestrians and comes with a large set of tools for scenario creation."





Cont.

> Current convert simulations/packages

- SUMO Netconvert
 - Convert network to SUMO, covers
 - VISUM, VISSIM, MATsim, Shapefile, OSM
 - \circ However
 - Manual work is suggested
- VISSIM import
 - Available to import Synchro files
 - However
 - Requires the latest version of Synchro
 - Multiple errors may occur if actual controller timing sheets not matched



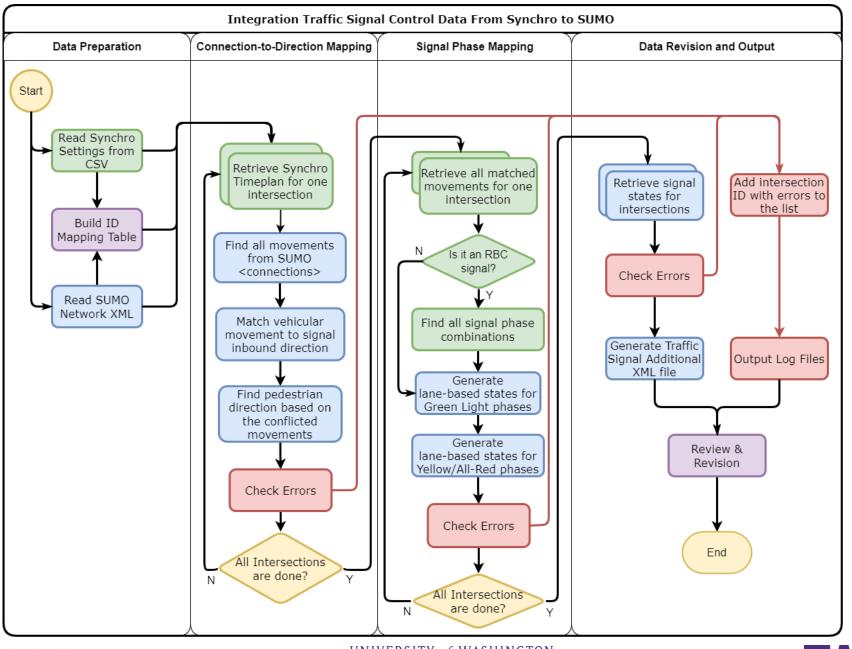


Traffic signal control integration – 4 stages

- **1. Data Preparation**
- 2. Connection-to-Direction Mapping
- 3. Signal Phase Mapping
- 4. Data Revision & Output









UNIVERSITY of WASHINGTON Intelligent Urban Transportation Systems W

Stage 1: Data Preparation

> Network data structure in Synchro

- Format: Comma-Separated Value Table (.csv)
- Network (General settings)
- Nodes (Geo-location of each intersection)
- Links (Settings for links)
 - # of lanes, distance, grade, speed, direction (e.g., NB, SB)
- Lanes (Detailed lane info)
 - Direction (NBL, NBT)
- Timeplans (Signal timing plans for each intersection)
 - Control type, cycle length, offset
- Phases (Signal phases each intersection)
 - o Min/Max Green, Yellow, Red, BRP



Stage 1: Data Preparation

> Network data structure in SUMO

- Format: XML
- Configuration (General settings)
- Edge (setting for edges)
 - Length, geo-location, ROW
- tlLogic (traffic light logics)
- Junction (settings for intersections)
 - o Intlanes, location
- Lane & Connection (relationship between two lanes)
 - Fromlanes, tolanes, direction





Synchro vs. SUMO

| Features | Synchro | SUMO |
|------------------|-----------------------------|---|
| | X Ped lanes | ✓ Ped lanes |
| | X Bus lanes X light rail | ✓ Bus lanes ✓ Light rail |
| Road Link | Link | Edge |
| | Lanes | Lane & Connections |
| | Nodes | Junction |
| Signal control | Timeplans & Phases | tlLogic |
| General settings | Network | configuration |



Stage 2: Connection-to-Direction Mapping



SUMO

sample

| | ID II | NBL | NBT | NBR | NBR2 | SBL2 | SBL | SBT | SBR | EBL | EBT | EBR | EBR2 | WBL2 | WBL | WBT | WBR | |
|--|----------------------------|----------------------------|-------------------------------|----------------------------------|--------|--------|----------------|-----------------|------------|---------|-----|-------------|--------|------|----------|-----|-----------|-----------|
| Jp Node | 6 | 8 | 8 | 3 | 8 | | | 7 | 7 | 7 | 3 | 3 | 3 | | | 9 | 9 | |
| Dest Node | 6 | 3 | | , | 9 | | | 9 | 8 | 3 | 7 | 9 | 8 | | | 8 | 3 | |
| anes | 6 | 0 | (|) | 0 | | | 0 | 1 | 0 | 1 | 2 | 0 | | | 1 | 1 | |
| Phase1 | 6 | | | | | | | | 4 | | 5 | 2 | | | | 1 | 6 | |
| PermPhas | 6 | | | | | | | 4 | | | 6 | | | | | 2 | | |
| Allow RTO | 6 | 1 | | | 1 | | | 1 | 1 | 1 | 1 | 1 | 1 | | | 1 | 1 | |
| Timeplans] | | | | | | | | | | | | | | | | | | |
| RECORDN IN | rid (| ATA | | | | | | | | | | | | | | | | |
| Control Ty | 6 | 3 | | | | | | | | | | | | | | | | |
| Cycle Len | 6 | 60 | | | | | | | | | | | | | | | | |
| Offset | 6 | 52 | | | | | | | | | | | ω | 100 | | | | |
| Phases] | | | | | | | | | | | | 536 | 5369 | | | | | |
| RECORDN IN | rid (| 01 | D2 | D3 | D4 | D5 | D6 | D7 | | | | > 8 | Ŭ, | * | | | | |
| BRP | 6 | 111 | 112 | 2 | l1 21 | 2 12 | 21 | 122 | 2 | | | 5 | 51 | | | | | |
| linGreen | 6 | 5 | 1 | , | | 7 | 5 | 7 | | | | #9 | #2 | | | | | |
| 1 axGreen | 6 | 8.5 | 17. | 5 | 21 | .5 6 | .5 | 19.5 | | | | | | | | | | |
| /ehExt | 6 | 3 | 0.2 | 2 | | 2 | 2 | 0.2 | | | | | , I | | | | | |
| ellow | 6 | 3.5 | 3.5 | i | 3 | .5 3 | .5 | 3.5 | | | | | | | | | | |
| AllRed | 6 | 0 | : | | | 1 | 0 | 1 | | | | <u>></u> | | * | | | | |
| tlLogic : <param 1<br=""/> <param 1<="" th=""/> <th>cey="m cey="d cey="p</th> <th>ax-gaj etecto assino</th> <th>p" valu pr-gap" g-time"</th> <th>e="3.(value value</th> <th>)"/></th> <th>/></th> <th>"0" t</th> <th>ype="ac</th> <th>¥ -2937</th> <th>53571#1</th> <th>Y B</th> <th></th> <th></th> <th></th> <th>Legend</th> <th>d</th> <th></th> <th></th> | cey="m cey="d cey="p | ax-gaj etecto assino | p" valu pr-gap" g-time" | e= "3.(value value |)"/> | /> | " 0 " t | ype=" ac | ¥ -2937 | 53571#1 | Y B | | | | Legend | d | | |
| | | | | | ue="fa | 100"/> | | | 293 | 30 | | * | 2 I V | | | _ | | |
| <param 1<="" td=""/> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>×.</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>33569015</td> <td>-</td> <td>lge ID</td> <td></td> | | | | | | | | | ×. | | | | | | 33569015 | - | lge ID | |
| <param 1<br=""/> <param 1<="" td=""/> <td>cev="f</td> <td></td> <td>(4)</td> <td></td> <td>1 8</td> <td>Co</td> <td>onnectior</td> <td>LinkIndex</td> | cev="f | | | | | | | | | | | | (4) | | 1 8 | Co | onnectior | LinkIndex |
| <param 1<="" td=""/> <td></td> <td>req" '</td> <td>/alue=</td> <td>500 //</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td><u>ن</u> ال</td> <td>ι Υ</td> <td>40</td> <td></td> <td>~</td> <td>onnectior</td> <td></td> | | req" ' | /alue= | 500 // | | | | | | | | <u>ن</u> ال | ι Υ | 40 | | ~ | onnectior | |

<connection from=":53073250_w2" to=":53073250_c1" fromLane="0" toLane="0" tl="53073250" linkIndex="8" dir="s" state="M"/>

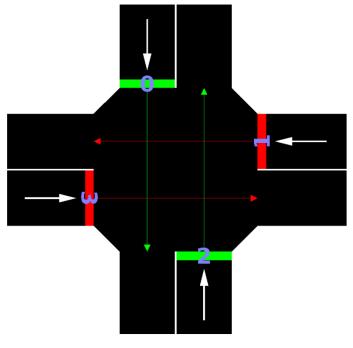




Stage 2: Connection-to-Direction Mapping

> Signal timing rule in SUMO

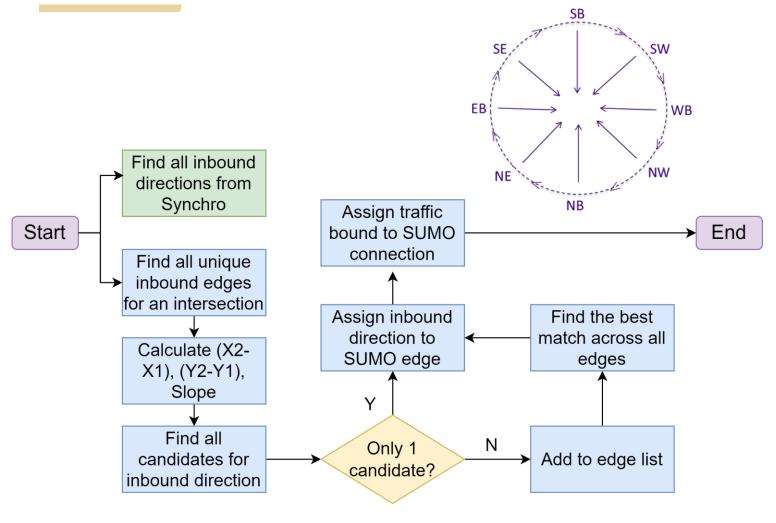
- Numbered in a clockwise pattern starting from 0 to 12 o'clock
- Pedestrian phases is specified after vehicle phases







Stage 2: Connection-to-Direction Mapping

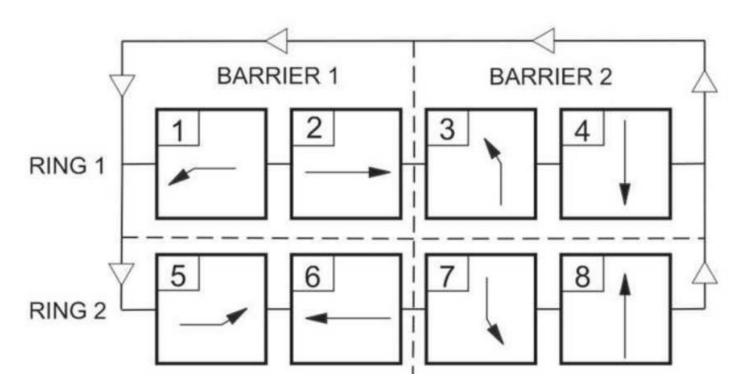






Stage 3: Signal Phase Mapping

> Ring barrier control







Stage 3: Signal Phase Mapping Signal timing setting in Synchro

| 🔶 🗁 🖽 🛱 🖕 🦘 | e = | | Synchro 1 | 10 - C:\Use | ers\dell\Desktop | o∖Traffic | ignal\Bigger | r_Seattle.syn | æ _ æ |
|----------------------------------|------------------------|---------------------------|---------------------|--------------------|------------------|-----------|--------------|---|------------------------------|
| File Home Opti | ons Transfer | Optimize Reports Help | | | | | | | |
| Map View | : ⊭ ¥ब्ब् : @ Q Q Q | View Ports Unane Settin | Volume Settings | Timing Settings | | nrrier | * | HCM 6th Ed ↓ Int. Results → ↓ Mvmt Results → ↑ Mvmt Results → ↑ Mvmt Results → ↑ Mvmt Results → ↑ Mvmt Results → | ults * |
| Mapping | Ta Zoom | View Options Lan | es & Volumes | | Signal Timing | | Detection | HCM 6th Edition HCM 2010 | Simulation Display Results |
| < 📰 \varTheta 🔶 🔶 🗙 | | | | | | | | 164 Western Ave | re & Western Ave W/Denny Way |
| NODE SETTINGS | | TIMING SETTINGS | EBT EBR WBL | ← WBT | NWL NWB | A PED | HOLD | | |
| de # | 164 | Lanes and Sharing (#RL) | ≜ ↑⊅ | <u>†††</u> | ሻሻሻ | - | - | | |
| one: | | Traffic Volume (vph) | 1033 67 0 |) 993 | 284 0 | — | — | | |
| East (ft): | 1264561 | Future Volume (vph) | 1033 67 0 |) 993 | 284 0 | 25 | 117 | | |
| North (ft): | 229386 | Turn Type | | | Prot — | — | — | | |
| Elevation (ft): | 0 | Protected Phases | 6 – – | 9 | m — | | 5 | | |
| escription | Ph9 = Ph2 w/ trailin | Permitted Phases | | | _ | — | — | | |
| ontrol Type | Pretimed | Permitted Flashing Yellow | | | | — | _ | | |
| ycle Length (s): | 140.0 | Detector Phases | 6 | - | 4 — | — | — | | |
| ock Timings: | | Switch Phase | 0 | | 0 — | — | _ | | |
| ptimize Cycle Length: | Optimize | Leading Detector (ft) | 0 | - | 0 — | — | — | | |
| ptimize Splits: | Optimize | Trailing Detector (ft) | 0 | | 0 — | - | _ | | |
| ctuated Cycle(s): | 140.0 | Minimum Initial (s) | 1.0 — — | | 7.0 — | — | 5.0 | | |
| atural Cycle(s): | 90.0 | Minimum Split (s) | 23.0 — — | | 24.0 — | - | 16.0 | | |
| ax v/c Ratio: | 0.91 | Total Split (s) | 68.0 — — | | 50.0 — | — | 22.0 | | |
| itersection Delay (s): | 25.0 | Yellow Time (s) | 3.5 — — | | 3.5 — | - | 3.5 | | |
| tersection LOS: | С | All-Red Time (s) | 6.0 — — | | 1.0 — | — | 6.0 | | |
| CU: | 0.61 | Lost Time Adjust (s) | 0.0 0.0 0.0 | | 0.0 0.0 | - | - | | |
| CULOS: | В | Lagging Phase? | | | | — | | | |
| iffset (s): | 50.0 | Allow Lead/Lag Optimize? | | | | — | | | |
| eferenced to: | TS2 - 1st Green | Recall Mode | Max — — 30 30 30 | | Max — 25 30 | - 30 | Max | | |
| eference Phase: 165 Ø2 (R) | 2+6 · FRT | Speed limit (mph) | <u> 30 30 3</u> 1 | <u>1 30</u> | 25 30 | 30 | 25 | #164#165 | |
|) s 164 | | | | | | | | 50 s | |
| | | | | | | | | | |
| ₩Ø6 (R) 3 s | | | | | 22 s | Ø5 | | | |
| 164#165 | | | | | 22.5 | | | | |
| ← → Ø9 | | | | | | | | | |
| -99 | | | | | | | | | |





Stage 3: Signal Phase Mapping Signal setting in SUMO

```
<tllogic id="0" programID="my_program" offset="0" type="actuated"

<param key="max-gap" value="3.0"/>

<param key="detector-gap" value="2.0"/>

<param key="passing-time" value="2.0"/>

<param key="show-detectors" value="false"/>

<param key="show-detectors" value="false"/>

<param key="file" value="NULL"/>

<param key="freq" value="300"/>

<phase duration="31" minDur="5" maxDur="45" state="GrGr"/>

....

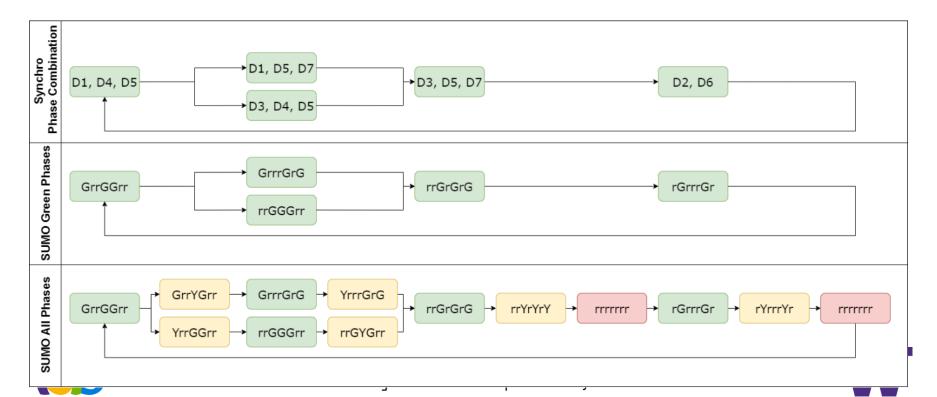
</tllogic>
```





Stage 3: Signal Phase Mapping

- > Find phase combination
- > Generate states for green phases
- > Generate Yellow/Red phases



Stage 4: Data Revision & Output

> Logging and Analysis

 Logs are generated detailing intersection IDs and causes of issues for further analysis.

> Validation and Quality Assurance

- Validation steps are integrated at each stage to ensure SUMO's signal phases align with those in Synchro.
- Checking conflict phases
- Discrepancies are identified, indicating possible misalignments.

> Manual Revisions

- Mismatched intersections necessitate manual revisions to correct misalignments.





Case Study: SUMO simulations in downtown Seattle Original network extracted from OSM

> Study region

- North: Mercer St
- South: Atlantic St
- West: Alaskan Way
- East: 12th Ave

> Available network feature

- Pedestrian lane
- Bus stop
- Link light rail
- TAZ





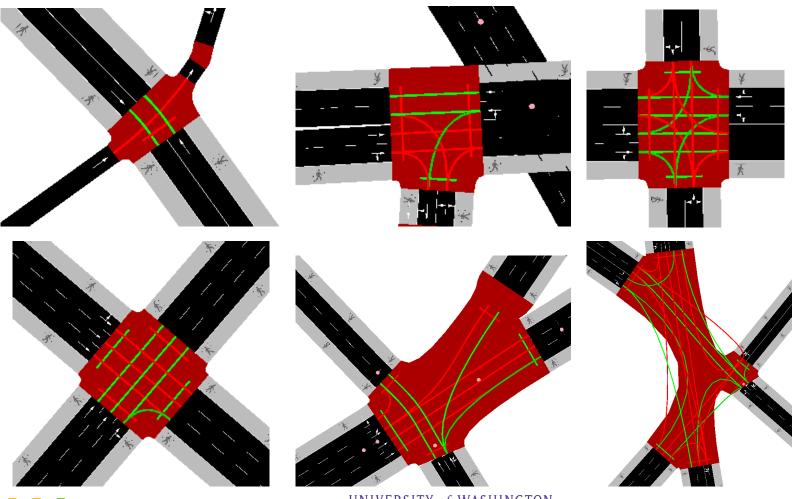
Case study







Diverse intersections in Downtown Seattle





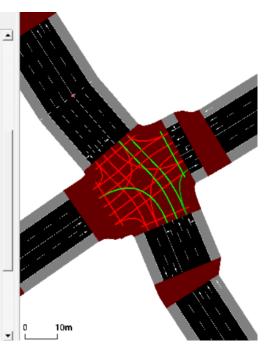


Results

Synchro

| Ø2 (R) | Øı | √ Ø3 | > 04 | |
|--------------|------|-------------|----------------|-----------------|
| 32 s | 20 s | 13 s | 35 s | |
| ↑ 05 ↓ 06 () | ٤) | ← Ø8 | | ▶ _{Ø7} |
| 13 s 39 s | | 35 s | | 13 s |

| Phases | | | | | | | | |
|--------|------|-------|----------------------|-------|------------------------|--|--|--|
| dur | min | max | state | nxt | name | | | |
| 5.00 | 5.00 | 8.50 | rrrrgGGGrrrrrrrrGrrr | 89 | (D2,D5) | | | |
| 5.00 | 5.00 | 8.50 | rrrrrrrGrrrrrrGrrrr | 10 | (D1,D5) | | | |
| 7.00 | 7.00 | 27.50 | rrrrgGGrrrrrgGGrGrGr | 11 | (D2,D6) | | | |
| 5.00 | 5.00 | 15.50 | rrrrrrrrrgGGGrrGr | 12 | (D1,D6) | | | |
| 5.00 | 5.00 | 8.50 | gGGGrrrrrrrrrrrG | 14 15 | (D3,D8) | | | |
| 7.00 | 7.00 | 30.50 | gGGrrrrrgGGrrrrrGrG | 16 | (D4,D8) | | | |
| 5.00 | 5.00 | 8.50 | rrrGrrrrrrGrrrrrrr | 17 | (D3,D7) | | | |
| 5.00 | 5.00 | 8.50 | rrrrrrrgGGGrrrrrGrr | 18 | (D4,D7) | | | |
| 3.50 | | | rrrryyyGrrrrrrrryrrr | 1 | (D2,D5)-(D1,D5)-Y | | | |
| 3.50 | | | rrrrgGGyrrrrrrrGrrr | 2 | (D2,D5)-(D2,D6)-Y | | | |
| 3.50 | | | rrrrrrryrrrrrrGrrrr | 3 | (D1,D5)-(D1,D6)-Y | | | |
| 3.50 | | | rrrryyyrrrrrgGGryrGr | 3 | (D2,D6)-(D1,D6)-Y | | | |
| 3.50 | | | rrrrrrrrryyyyrryr | 13 | (D1,D6)-(D3,D8)-Y | | | |
| 1.00 | | | rrrrrrrrrrrrrrrr | 4 | (D1,D6)-(D3,D8)-R | | | |
| 3.50 | | | gGGyrrrrrrrrrrrG | 5 | (D3,D8)-(D4,D8)-Y | | | |
| 3.50 | | | yyyGrrrrrrrrrrry | 6 | (D3,D8)-(D3,D7)-Y | | | |
| 3.50 | | | yyyrrrrrgGGrrrrrGry | 7 | (D4,D8)-(D4,D7)-Y | | | |
| 3.50 | | | rrryrrrrrrGrrrrrrr | 7 | (D3,D7)-(D4,D7)-Y | | | |
| 3.50 | | | rrrrrrryyyyrrrrryrr | 19 | (D4,D7)-(D2,D5)-Y | | | |
| 1.00 | | | rrrrrrrrrrrrrrrrr | 0 | (D4, D7) - (D2, D5) -R | | | |





Signal integration results

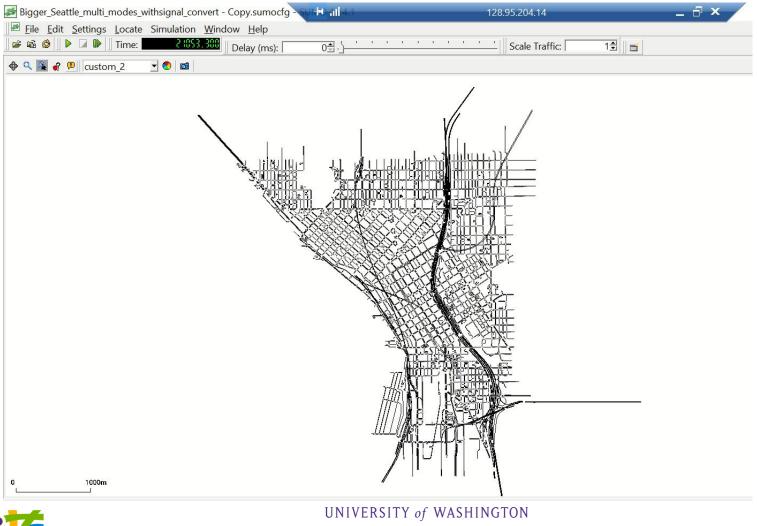
| Scenario | | Successful Converted Intersections | Success Rate |
|-----------------------------|-----|--|-----------------|
| Dearborn Street Arterial | 5 | 5 | 100% |
| Downtown Seattle | 281 | 239 | 85.1% |





168 TAZs 39286 edges

Simulation display





Intelligent Urban Transportation Systems



Conclusion & Future Step

> Conclusion

- Proposed four-stage approach and the integration Process
 Examined
- Developed a semi-automated pipeline in Python
- Tested on two Synchro models in downtown Seattle with an 85% success rate

> Future Step

- Framework Expansion
- Algorithmic Enhancements (for higher accuracy)
- Advanced Features (Coordinated signal control)
- Broader Integration Goals (not just traffic signal)





THANKS! QUESTIONS & COMMENTS?



Intelligent Urban Transportation Systems UNIVERSITY of WASHINGTON